

Evoluzione della varianza della posizione  
nel tempo nel pacchetto gaussiano  
usando le metodi di Heisenberg

①

Equazioni del moto per gli operatori

$$\frac{d\hat{X}}{dt} = \frac{\hat{P}}{m} \quad \frac{d\hat{P}}{dt} = 0$$

soluzione

$$\begin{cases} \hat{X}(t) = \hat{X}(0) + \frac{\hat{P}(0)}{m} t \\ \hat{P}(t) = \hat{P}(0) \end{cases} \quad \underline{p \text{ conservato}}$$

calcoliamo prima

$$\langle \hat{P}^2(t) \rangle = \langle P(0)^2 \rangle$$

$$\langle \hat{P}(t) \rangle = \langle \hat{P}(0) \rangle = \frac{\hbar k_0}{m}$$

$$\langle \hat{P}^2(t) \rangle - \langle P(t) \rangle^2 = \langle \hat{P}(0)^2 \rangle - \langle P(0) \rangle^2 = \sigma_P = \frac{\hbar^2}{4\sigma_x^2}$$

indipendente del tempo p conservato

$$\begin{aligned} \langle \hat{X}^2(t) \rangle &= \left\langle \left( \hat{X}(0) + \frac{\hat{P}(0)}{m} t \right)^2 \right\rangle = \\ &= \left\langle X(0)^2 + \frac{\hat{P}(0)^2}{m^2} t^2 + \frac{t}{m} (X P + P X) \right\rangle \end{aligned}$$

$$\langle X(t) \rangle = \langle X(0) \rangle + \frac{\langle P(0) \rangle}{m} t$$

(2)

$$\langle \Delta x^2(t) \rangle = \langle x(t)^2 \rangle - \langle x(t) \rangle^2 =$$

$$= \langle x(0)^2 \rangle - \langle x(0) \rangle^2 + \frac{t^2}{m^2} (\langle p^2 \rangle - \langle p \rangle^2) +$$

$$+ \frac{t}{m} \langle xp + px \rangle - 2 \frac{t}{m} \langle x \rangle \langle p \rangle$$

$$\langle xp + px \rangle = \langle xp + (xp)^\dagger \rangle = 2 \operatorname{Re} \langle xp \rangle$$

$$\langle xp \rangle = \int dx \psi^*(x) x \left( -i\hbar \frac{\partial}{\partial x} \right) \psi(x)$$

$$\psi(x) = \psi_0(x-x_0) e^{ik_0 x} \quad \text{radice della funzione gaussiana}$$

$$\psi'(x) = \psi_0'(x-x_0) e^{ik_0 x} + ik_0 \psi(x)$$

$$\langle xp \rangle = \int dx \psi_0 x \left[ \psi_0' + ik_0 \psi_0 \right]$$

$$2 \operatorname{Re} \langle xp \rangle = 2 \operatorname{Re} \left[ -i\hbar \int dx \psi_0(x-x_0) x \psi_0'(x-x_0) + \right. \\ \left. + \left( \int dx \psi_0(x-x_0) x \psi_0(x-x_0) \right) \hbar k_0 \right]$$

$$2 \operatorname{Re} \langle xp \rangle = 2\hbar k_0 \langle x_0 \rangle$$

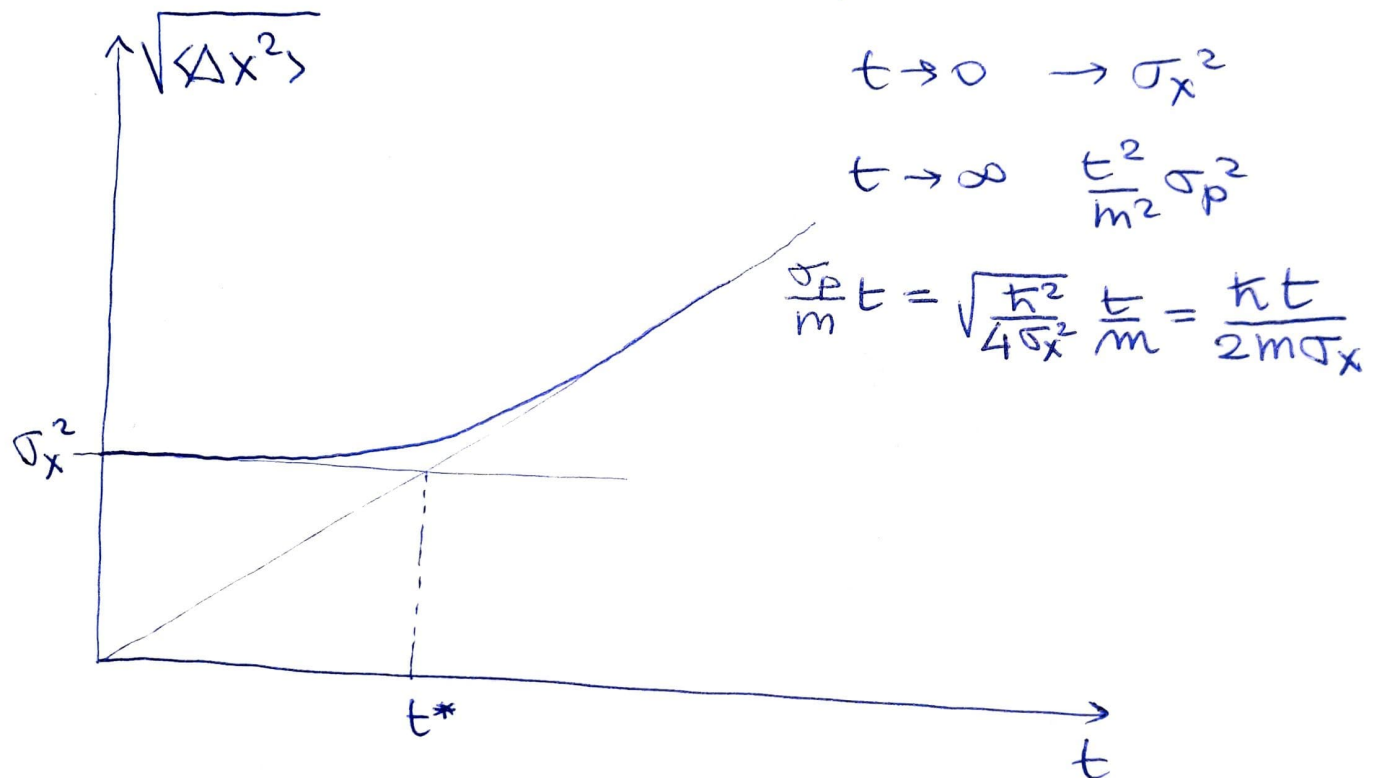
$$\langle \Delta x^2(t) \rangle = \langle \Delta x^2(0) \rangle + \frac{t^2}{m^2} \sigma_p^2 + \cancel{\frac{t}{m} 2\hbar k_0 x_0} - \cancel{2 \frac{t}{m} x_0 \hbar k_0}$$

$$\langle \Delta x^2(t) \rangle = \sigma_x^2 + \frac{t^2}{m^2} \sigma_p^2 = \sigma_x^2 \left( 1 + \frac{t^2}{m^2} \frac{\sigma_p^2}{\sigma_x^2} \right)$$

$$\langle \Delta X^2(t) \rangle = \sigma_x^2 \left( 1 + \frac{t^2}{m^2} \frac{\hbar^2}{4\sigma_x^4} \right)$$

$$\langle \Delta X^2(t) \rangle = \sigma_x^2 \left( 1 + \left( \frac{\hbar t}{2m\sigma_x^2} \right)^2 \right)$$

$$\langle \Delta X^2(t) \rangle = \sigma_x^2 \left( 1 + \frac{t^2}{m^2} \frac{\sigma_p^2}{\sigma_x^2} \right)$$



$$t^* : \frac{t^2}{m^2} \sigma_p^2 = \sigma_x^2 \quad t^* = \frac{m\sigma_x}{\sigma_p} = \frac{m\sigma_x}{\sqrt{\frac{\hbar^2}{4\sigma_x^2}}}$$

$$t^* = \frac{\sqrt{2} m \sigma_x^2}{\hbar}$$

confrontare con la legge della diffusione ( $d=1$ )

$$\langle \Delta X^2(t) \rangle = 2Dt \Rightarrow \sqrt{\langle \Delta X^2(t) \rangle} = \sqrt{2Dt}$$